

# Non-absolutely convergent integrals with respect to distributions

Jan MALÝ

Charles University, Prague

Symposium in Real Analysis XXXVII (Sugarcane Symposium),  
Universidade de São Paulo, São Carlos, June 3-6, 2013

# Nonabsolutely convergent integrals

Professional nonabsolutely convergent integrals: include the Lebesgue integral and integrate all derivatives.

# Nonabsolutely convergent integrals

Professional nonabsolutely convergent integrals: include the Lebesgue integral and integrate all derivatives.

Nonabsolutely convergent integration

- allows a wider class of integrable functions
- but

# Nonabsolutely convergent integrals

Professional nonabsolutely convergent integrals: include the Lebesgue integral and integrate all derivatives.

Nonabsolutely convergent integration

- allows a wider class of integrable functions
- but
- requires an additional structure.

# Nonabsolutely convergent integrals

Professional nonabsolutely convergent integrals: include the Lebesgue integral and integrate all derivatives.

Nonabsolutely convergent integration

- allows a wider class of integrable functions
- but
- requires an additional structure.

For example, to give a sense to the nonabsolutely convergent sum

$$\sum_{n=1}^{\infty} \frac{(-1)^n}{n}$$

we need the ordering of the set of natural numbers, a permutation of the summands can lead to a different result.

# Nonabsolutely convergent integrals

Professional nonabsolutely convergent integrals: include the Lebesgue integral and integrate all derivatives.

Nonabsolutely convergent integration

- allows a wider class of integrable functions
- but
- requires an additional structure.

For example, to give a sense to the nonabsolutely convergent sum

$$\sum_{n=1}^{\infty} \frac{(-1)^n}{n}$$

we need the ordering of the set of natural numbers, a permutation of the summands can lead to a different result. Similarly, to give a sense to the integral

$$\int_0^{\infty} \frac{\sin x}{x} dx$$

and to others nonabsolutely convergent integrals, we need the ordering of the real line.

$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

Stieltjes version (integration with respect to  $g$ )

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{g(y) - g(x)} = 0.$$



$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

Stieltjes version (integration with respect to  $g$ )

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{g(y) - g(x)} = 0.$$

Good if  $g$  is strictly monotone, otherwise the denominator can degenerate, better

$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

Stieltjes version (integration with respect to  $g$ )

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{g(y) - g(x)} = 0.$$

Good if  $g$  is strictly monotone, otherwise the denominator can degenerate, better

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{V_g(y) - V_g(x)} = 0,$$

where  $V_g$  is the variation of  $g$ .

$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

Stieltjes version (integration with respect to  $g$ )

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{g(y) - g(x)} = 0.$$

Good if  $g$  is strictly monotone, otherwise the denominator can degenerate, better

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{V_g(y) - V_g(x)} = 0,$$

where  $V_g$  is the variation of  $g$ . But what if  $g$  is not of finite variation?

$F$  is an indefinite “Newton” integral of  $f : (a, b) \rightarrow \mathbb{R}$  if, for each  $x \in (a, b)$ ,

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(y - x)}{y - x} = 0.$$

Stieltjes version (integration with respect to  $g$ )

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{g(y) - g(x)} = 0.$$

Good if  $g$  is strictly monotone, otherwise the denominator can degenerate, better

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{V_g(y) - V_g(x)} = 0,$$

where  $V_g$  is the variation of  $g$ . But what if  $g$  is not of finite variation?  
And what concerning more general integrands

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - U(x, y) - U(x, x)}{???) = 0 ?$$

## Definition (H. Bendová and J.M. 2011)

Let  $I = (a, b) \subset \mathbb{R}$  be an interval. We say that  $F: I \rightarrow \mathbb{R}$  is an *indefinite MC-integral* of  $f: I \rightarrow \mathbb{R}$  with respect to  $g: I \rightarrow \mathbb{R}$  if there is a strictly increasing function  $\xi: I \rightarrow \mathbb{R}$  (the so-called *control function*) such that

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{\xi(y) - \xi(x)} = 0$$

for each  $x \in I$ .

## Definition (H. Bendová and J.M. 2011)

Let  $I = (a, b) \subset \mathbb{R}$  be an interval. We say that  $F: I \rightarrow \mathbb{R}$  is an *indefinite MC-integral* of  $f: I \rightarrow \mathbb{R}$  with respect to  $g: I \rightarrow \mathbb{R}$  if there is a strictly increasing function  $\xi: I \rightarrow \mathbb{R}$  (the so-called *control function*) such that

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{\xi(y) - \xi(x)} = 0$$

for each  $x \in I$ .

The resulting indefinite integral does not depend on the choice of the control function (among working ones). It is equivalent to the Kurzweil-Henstock-Stieltjes integral.

## Definition (H. Bendová and J.M. 2011)

Let  $I = (a, b) \subset \mathbb{R}$  be an interval. We say that  $F: I \rightarrow \mathbb{R}$  is an *indefinite MC-integral* of  $f: I \rightarrow \mathbb{R}$  with respect to  $g: I \rightarrow \mathbb{R}$  if there is a strictly increasing function  $\xi: I \rightarrow \mathbb{R}$  (the so-called *control function*) such that

$$\lim_{y \rightarrow x} \frac{F(y) - F(x) - f(x)(g(y) - g(x))}{\xi(y) - \xi(x)} = 0$$

for each  $x \in I$ .

The resulting indefinite integral does not depend on the choice of the control function (among working ones). It is equivalent to the Kurzweil-Henstock-Stieltjes integral.

It is clear that this integral contains the Newtonian one. But why it is so much better? We can use the variable growth of the control function to override singularities.

# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?



# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?

Yes, but it is not as natural anymore!

# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?

Yes, but it is not as natural anymore!

Consider class  $\mathcal{A}$  of subsets of  $\mathbb{R}^n$  and a function  $\mathbf{F} : \mathcal{A} \rightarrow \mathbb{R}$ , where  $\mathbf{F}(A)$  has the meaning of a generalized integral  $\int_A f(x) dx$ .

# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?

Yes, but it is not as natural anymore!

Consider class  $\mathcal{A}$  of subsets of  $\mathbb{R}^n$  and a function  $\mathbf{F} : \mathcal{A} \rightarrow \mathbb{R}$ , where  $\mathbf{F}(A)$  has the meaning of a generalized integral  $\int_A f(x) dx$ .

For abstract Lebesgue integration the indedinite integral is just the function

$$E \mapsto \int_E f d\mu, \quad E \text{ measurable.}$$

# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?

Yes, but it is not as natural anymore!

Consider class  $\mathcal{A}$  of subsets of  $\mathbb{R}^n$  and a function  $\mathbf{F} : \mathcal{A} \rightarrow \mathbb{R}$ , where  $\mathbf{F}(A)$  has the meaning of a generalized integral  $\int_A f(x) dx$ .

For abstract Lebesgue integration the indedinite integral is just the function

$$E \mapsto \int_E f d\mu, \quad E \text{ measurable.}$$

If we want to gain some nonabsolutely convergent integrands, we need to restrict the family of sets in accordance with the additional structure.

# Multidimensional case

Can we represent the indefinite integral by a function  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  as in the one dimensional case?

Yes, but it is not as natural anymore!

Consider class  $\mathcal{A}$  of subsets of  $\mathbb{R}^n$  and a function  $\mathbf{F} : \mathcal{A} \rightarrow \mathbb{R}$ , where  $\mathbf{F}(A)$  has the meaning of a generalized integral  $\int_A f(x) dx$ .

For abstract Lebesgue integration the indedinite integral is just the function

$$E \mapsto \int_E f d\mu, \quad E \text{ measurable.}$$

If we want to gain some nonabsolutely convergent integrands, we need to restrict the family of sets in accordance with the additional structure.

Choose first  $\mathcal{A}$  to be the family of all bounded  $n$ -dimensional [intervals](#).

Choose first  $\mathcal{A}$  to be the family of all bounded  $n$ -dimensional **intervals**.

**Advantage:** It is a simple class, admits partitions.

Choose first  $\mathcal{A}$  to be the family of all bounded  $n$ -dimensional **intervals**.

**Advantage:** It is a simple class, admits partitions.

**Disdvantage:** Not invariant with respect to changes of coordinates (the less for a nonlinear change of variables).



Choose first  $\mathcal{A}$  to be the family of all bounded  $n$ -dimensional [intervals](#).

**Advantage:** It is a simple class, admits partitions.

**Disdvantage:** Not invariant with respect to changes of coordinates (the less for a nonlinear change of variables).

The link to the one-dimensional case:

$$F(b) - F(a) = \mathbf{F}([a, b]), \quad 0 < a \leq b < \infty.$$

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

Other versions for  $\mathcal{A}$ : [simplices](#), [polyhedra](#), [convex sets](#).

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

Other versions for  $\mathcal{A}$ : **simplices, polyhedra, convex sets**. **Advantage:** Affine change of variables

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

Other versions for  $\mathcal{A}$ : **simplices, polyhedra, convex sets**. **Advantage:** Affine change of variables

**Disdvantage:** Not as simple, and still problems with a nonlinear change of variables.

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

Other versions for  $\mathcal{A}$ : **simplices, polyhedra, convex sets**. **Advantage:** Affine change of variables

**Disdvantage:** Not as simple, and still problems with a nonlinear change of variables.

Choose  $\mathcal{A}$  to be **BV sets** (sets of finite perimeter) (series of works by W. Pfeffer)

The game with regularity of intervals: to achieve that the integral integrates all derivatives (J. Mawhin 1981,...)

Other versions for  $\mathcal{A}$ : **simplices, polyhedra, convex sets**. **Advantage:** Affine change of variables

**Disdvantage:** Not as simple, and still problems with a nonlinear change of variables.

Choose  $\mathcal{A}$  to be **BV sets** (sets of finite perimeter) (series of works by W. Pfeffer)

**Advantages:** bilipschitz change of variables, integrates all derivatives.

# Functional approach to indefinite integral

Idea: Indefinite integral is not

$$A \mapsto \int_A f(x) dx$$

where  $A$  runs over a family of sets, but

$$\varphi \mapsto \int_{\mathbb{R}^n} f(x)\varphi(x) dx$$

where  $\varphi$  runs over a family of functions.



# Functional approach to indefinite integral

**Idea:** Indefinite integral is not

$$A \mapsto \int_A f(x) dx$$

where  $A$  runs over a family of sets, but

$$\varphi \mapsto \int_{\mathbb{R}^n} f(x)\varphi(x) dx$$

where  $\varphi$  runs over a family of functions.

Analogously to Radon-Nikodým differentiation of measures with respect to measures, we differentiate distributions with respect to distributions and our indefinite integral is the inverse process.

# Functional approach to indefinite integral

Idea: Indefinite integral is not

$$A \mapsto \int_A f(x) dx$$

where  $A$  runs over a family of sets, but

$$\varphi \mapsto \int_{\mathbb{R}^n} f(x)\varphi(x) dx$$

where  $\varphi$  runs over a family of functions.

Analogously to Radon-Nikodým differentiation of measures with respect to measures, we differentiate distributions with respect to distributions and our indefinite integral is the inverse process.

So the indefinite integral of

“ $f$ , regarded as a function” is “ $f$ , regarded as a distribution”.

# Functional approach to indefinite integral

Idea: Indefinite integral is not

$$A \mapsto \int_A f(x) dx$$

where  $A$  runs over a family of sets, but

$$\varphi \mapsto \int_{\mathbb{R}^n} f(x)\varphi(x) dx$$

where  $\varphi$  runs over a family of functions.

Analogously to Radon-Nikodým differentiation of measures with respect to measures, we differentiate distributions with respect to distributions and our indefinite integral is the inverse process.

So the indefinite integral of

“ $f$ , regarded as a function” is “ $f$ , regarded as a distribution”.

Now, nonabsolutely convergent integration means that we can assign a distribution to a function which is not locally Lebesgue integrable.

A version of the functional approach was **PU integral**: Instead of partition into intervals we can use partitions of unity into functions. This idea is due to J. Jarník and J. Kurzweil (1985, 1988), improved by J. Kurzweil, J. Mawhin, W. Pfeffer (1991).

# Integrands

We distinguish three levels of generality of integrands: classical integrands (integration with respect to the Lebesgue measure), Stieltjes integrands and general integrands.

We distinguish three levels of generality of integrands: classical integrands (integration with respect to the Lebesgue measure), Stieltjes integrands and general integrands.

We will illustrate this on the real line:

**Classical integrands**  $f dx$ :  $F(y) - F(x) \sim f(x)(y - x)$ .

We distinguish three levels of generality of integrands: classical integrands (integration with respect to the Lebesgue measure), Stieltjes integrands and general integrands.

We will illustrate this on the real line:

**Classical integrands**  $f dx$ :  $F(y) - F(x) \sim f(x)(y - x)$ .

**Stieltjes integrands**  $f dg$ :  $F(y) - F(x) \sim f(x)(g(y) - g(x))$ .

We distinguish three levels of generality of integrands: classical integrands (integration with respect to the Lebesgue measure), Stieltjes integrands and general integrands.

We will illustrate this on the real line:

**Classical integrands**  $f dx$ :  $F(y) - F(x) \sim f(x)(y - x)$ .

**Stieltjes integrands**  $f dg$ :  $F(y) - F(x) \sim f(x)(g(y) - g(x))$ .

**General integrands**  $DU$ ;  $F(y) - F(x) \sim U(x, y) - U(x, x)$ .

Studied e.g. by J. Kurzweil (in connection with GODEs), R. Henstock.



In the functional approach, the general integrand is a variable  $x \mapsto \mathcal{G}(x) : \Omega \rightarrow \mathcal{D}'(\Omega)$ . The indefinite integral is a distribution  $\mathcal{F}$  such that

$$\mathcal{F}(\varphi) \sim \mathcal{G}(x)(\varphi)$$

if  $\varphi$  is supported in a small neighborhood of  $x$ .

In the functional approach, the general integrand is a variable  $x \mapsto \mathcal{G}(x) : \Omega \rightarrow \mathcal{D}'(\Omega)$ . The indefinite integral is a distribution  $\mathcal{F}$  such that

$$\mathcal{F}(\varphi) \sim \mathcal{G}(x)(\varphi)$$

if  $\varphi$  is supported in a small neighborhood of  $x$ .

### Examples

A Stieltjes integrand  $\mathcal{G}(x) = f(x)\mu$

$$\mathcal{G}(x)(\varphi) = \int_{\Omega} f(x)\varphi(y) d\mu(y).$$

We can replace the Radon measure  $\mu$  by a distribution.

In the functional approach, the general integrand is a variable  $x \mapsto \mathcal{G}(x) : \Omega \rightarrow \mathcal{D}'(\Omega)$ . The indefinite integral is a distribution  $\mathcal{F}$  such that

$$\mathcal{F}(\varphi) \sim \mathcal{G}(x)(\varphi)$$

if  $\varphi$  is supported in a small neighborhood of  $x$ .

### Examples

A Stieltjes integrand  $\mathcal{G}(x) = f(x)\mu$

$$\mathcal{G}(x)(\varphi) = \int_{\Omega} f(x)\varphi(y) d\mu(y).$$

We can replace the Radon measure  $\mu$  by a distribution.

A varifold type structure:  $G_k(\mathbb{R}^n)$  is the Grassmannian manifold,  $\mu$  is a measure on  $\mathbb{R}^n \times G_k(\mathbb{R}^n)$  disintegrated into  $(\mu_x)_{x \in \mathbb{R}^n}$ :

$$\mathcal{G}(x)(\varphi) = \int_{G_k(\mathbb{R}^n)} \left( \int_V \varphi(x+y) d\mathcal{H}^k(y) \right) d\mu_x(V).$$

Here, the integration of the test function over the curved surface is replaced by the integration over the tangent space.

# Definitions

We prepare for a definition in style of [variational](#) or [strong Kurzweil-Henstock](#) integration. However, we cannot rely on reasonable partitioning behavior of our system of sets,

# Definitions

We prepare for a definition in style of [variational](#) or [strong Kurzweil-Henstock](#) integration. However, we cannot rely on reasonable partitioning behavior of our system of sets, namely, we use **balls!** This is important for later generalization to metric spaces.

# Definitions

We prepare for a definition in style of **variational** or **strong Kurzweil-Henstock** integration. However, we cannot rely on reasonable partitioning behavior of our system of sets, namely, we use **balls!** This is important for later generalization to metric spaces.

We consider a family  $(\mathbf{p}_{x,r})_{x,r}$  of norms on  $\mathcal{D} = \mathcal{D}(\Omega)$  related to balls  $B(x, r)$ , we skip precise assumptions, the model example is

$$\begin{aligned}\mathbf{p}_{x,r}(\varphi) &= r^k \|D^{(k)}\varphi\|_\infty, \\ \varphi &\in \mathcal{D}, \text{ spt } \varphi \subset \overline{B}(x, r).\end{aligned}$$

Here  $k$  is a given order of differentiation and  $|D^{(k)}\varphi(x)|$  is the  $k$ -th order total differential of  $\varphi$ .

# Definitions

We prepare for a definition in style of **variational** or **strong Kurzweil-Henstock** integration. However, we cannot rely on reasonable partitioning behavior of our system of sets, namely, we use **balls!** This is important for later generalization to metric spaces.

We consider a family  $(\mathbf{p}_{x,r})_{x,r}$  of norms on  $\mathcal{D} = \mathcal{D}(\Omega)$  related to balls  $B(x, r)$ , we skip precise assumptions, the model example is

$$\begin{aligned}\mathbf{p}_{x,r}(\varphi) &= r^k \|D^{(k)}\varphi\|_\infty, \\ \varphi &\in \mathcal{D}, \text{ spt } \varphi \subset \overline{B}(x, r).\end{aligned}$$

Here  $k$  is a given order of differentiation and  $|D^{(k)}\varphi(x)|$  is the  $k$ -th order total differential of  $\varphi$ . The dual norm is

$$\begin{aligned}\mathbf{p}_{x,r}^*(\mathcal{T}) &= \sup \left\{ \langle \mathcal{T}, \varphi \rangle : \varphi \in \mathcal{D}(\mathbb{R}^n), \text{ spt } \varphi \subset B(x, r), \mathbf{p}_{x,r}(\varphi) \leq 1 \right\}, \\ \mathcal{T} &\in \mathcal{D}'(\mathbb{R}^n).\end{aligned}$$

A function  $\delta : \Omega \rightarrow (0, \infty)$  is termed a *gauge*. A finite system  $(B(x_i, r_i))_{i=1}^m$  of balls is called an  $\alpha$ -*packing* in  $\Omega$  if the balls  $B(x_i, \alpha r_i)$  are pairwise disjoint and contained in  $\Omega$ ,  $i = 1, \dots, m$ . Given a gauge  $\delta$ , we say that the  $\alpha$ -packing is  $\delta$ -*fine* if  $r_i < \delta(x_i)$ ,  $i = 1, \dots, m$ .



A function  $\delta : \Omega \rightarrow (0, \infty)$  is termed a *gauge*. A finite system  $(B(x_i, r_i))_{i=1}^m$  of balls is called an  $\alpha$ -*packing* in  $\Omega$  if the balls  $B(x_i, \alpha r_i)$  are pairwise disjoint and contained in  $\Omega$ ,  $i = 1, \dots, m$ . Given a gauge  $\delta$ , we say that the  $\alpha$ -packing is  $\delta$ -*fine* if  $r_i < \delta(x_i)$ ,  $i = 1, \dots, m$ .

The purpose of the scaling factor  $\alpha$  is to overturn the dependence of the integral on the geometry of balls and to enable bilipschitz change of variables.

## Definition (J.M; P. Honzík and J.M.)

Let  $\mathcal{F}$  be a distribution on  $\Omega$  and  $(\mathcal{G}(x))_{x \in \Omega}$  be a system of distributions on  $\Omega$  (standard choice  $\mathcal{G}(x) = f(x)\mathcal{G}$ ). We say that  $\mathcal{F}$  is an indefinite packing integral of  $(\mathcal{G}(x))_{x \in \Omega}$  (with respect to the family  $(\mathbf{p}_{x,r})_{x,r}$ , if there exist  $\alpha \geq 1$  such that for each  $\varepsilon > 0$  there exists a gauge  $\delta : I \rightarrow (0, \infty)$  such that for each  $\delta$ -fine  $\alpha$ -packing  $(B(x_i, r_i))_{i=1}^m$  in  $\Omega$  we have

$$\sum_{i=1}^m \mathbf{p}_{x_i, r_i}^*(\mathcal{F} - \mathcal{G}(x_i)) < \varepsilon.$$

If  $\mathcal{G}(x)$  has the form  $f(x)\mathcal{G}$  where  $f$  is a function and  $\mathcal{G}$  a distribution, we say that  $\mathcal{F}$  is an indefinite packing integral of the function  $f$  w.r.t. the distribution  $\mathcal{G}$ . Then we denote the integral by  $\int f d\mathcal{G}$ . We also use the multiplier notation  $f \bullet \mathcal{G} = \int f d\mathcal{G}$ .

- The packing integral is well defined (this means unique, see the next page).

- The packing integral is well defined (this means unique, see the next page).
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.

- The packing integral is well defined (this means unique, see the next page).
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.
- The Kurzweil-Henstock integral on the real line is also included. Further comparison of various related integrals on the real line brings numerous open questions.

- The packing integral is well defined (this means unique, see the next page).
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.
- The Kurzweil-Henstock integral on the real line is also included. Further comparison of various related integrals on the real line brings numerous open questions.
- The packing integral integrates all derivatives

- The packing integral is well defined (this means unique, see the next page).
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.
- The Kurzweil-Henstock integral on the real line is also included. Further comparison of various related integrals on the real line brings numerous open questions.
- The packing integral integrates all derivatives
- The packing integral allows for a bilipschitz change of variables.

- The packing integral is well defined (this means unique, see the next page).
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.
- The Kurzweil-Henstock integral on the real line is also included. Further comparison of various related integrals on the real line brings numerous open questions.
- The packing integral integrates all derivatives
- The packing integral allows for a bilipschitz change of variables.
- Applications to singular integrals (P. Honzík and J.M.). We extend the class of functions which admit a Riesz transform by means of integration with respect to the singular kernel distribution.



## Theorem

*The indefinite packing integral of a family of distribution is unique.*

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

- We may assume that we integrate just 0.

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

- We may assume that we integrate just 0.
- Given and  $\varepsilon > 0$ , we find the corresponding gage  $\delta$ .

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

- We may assume that we integrate just 0.
- Given and  $\varepsilon > 0$ , we find the corresponding gage  $\delta$ .
- We use a telescopic argument to find good  $\delta$ -fine radii, on which the dual norm is almost doubling.

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

- We may assume that we integrate just 0.
- Given and  $\varepsilon > 0$ , we find the corresponding gage  $\delta$ .
- We use a telescopic argument to find good  $\delta$ -fine radii, on which the dual norm is almost doubling.
- We use Vitali type covering argument to find a covering by balls  $B(x, r)$  such that  $B(x, r/5)$  are disjointed.

## Theorem

*The indefinite packing integral of a family of distribution is unique.*

Idea of the proof:

- We may assume that we integrate just 0.
- Given  $\varepsilon > 0$ , we find the corresponding gage  $\delta$ .
- We use a telescopic argument to find good  $\delta$ -fine radii, on which the dual norm is almost doubling.
- We use Vitali type covering argument to find a covering by balls  $B(x, r)$  such that  $B(x, r/5)$  are disjointed.
- Then we construct a partition of unity related to the selected balls.

## Theorem (K. Kuncová and J.M.)

$\mathcal{F}$  is an indefinite packing integral of  $(\mathcal{G}(x))_{x \in \Omega}$  w.r.t.  $(\mathbf{p}_{x,r})_{x,r}$  if and only if there exist a Radon measure  $\mu$  on  $\Omega$  and  $\alpha \geq 1$  such that

$$\lim_{r \rightarrow 0^+} \frac{\mathbf{p}_{x,r}^*(\mathcal{F} - \mathcal{G}(x))}{\mu(B(x, \alpha r))} = 0.$$



## Theorem (K. Kuncová and J.M.)

$\mathcal{F}$  is an indefinite packing integral of  $(\mathcal{G}(x))_{x \in \Omega}$  w.r.t.  $(\mathbf{p}_{x,r})_{x,r}$  if and only if there exist a Radon measure  $\mu$  on  $\Omega$  and  $\alpha \geq 1$  such that

$$\lim_{r \rightarrow 0^+} \frac{\mathbf{p}_{x,r}^*(\mathcal{F} - \mathcal{G}(x))}{\mu(B(x, \alpha r))} = 0.$$

The proof use a method invented by M. Csörnyei in a different context.

# Gauss-Green theorem

In a series of papers and books, W. Pfeffer proves a general Gauss-Green theorem

$$\int_{\Omega} \operatorname{div} \mathbf{f}(x) \, dx = \int_{\partial\Omega} \mathbf{f} \cdot d\nu.$$

The indefinite integral in his work is a function of BV set, a charge.  
Functional approach to charges: T. De Pauw and W. Pfeffer 2008, T. De Pauw, R. Hardt, L. Moonens,...

In the Pfeffer divergence theorem,  $\Omega$  is a set of finite perimeter, the interior integral is nonabsolutely convergent, but the boundary integral is absolutely convergent.

In the Pfeffer divergence theorem,  $\Omega$  is a set of finite perimeter, the interior integral is nonabsolutely convergent, but the boundary integral is absolutely convergent.

The boundary integral is with respect to the distributional derivative  $-\nu$  of the characteristic function  $\chi_\Omega$  of  $\Omega$ .

In the Pfeffer divergence theorem,  $\Omega$  is a set of finite perimeter, the interior integral is nonabsolutely convergent, but the boundary integral is absolutely convergent.

The boundary integral is with respect to the distributional derivative  $-\nu$  of the characteristic function  $\chi_\Omega$  of  $\Omega$ .

Now, we know how to integrate with respect to distributions and can to handle integrals with respect to  $\nu$  even if  $\nu$  is not a measure.

Our aim is to prove that

$$\int \mathbf{f} d(D\chi_\Omega) + \int \chi_\Omega d(\operatorname{Div} \mathbf{f}) = \operatorname{Div} \int \mathbf{f} \chi_\Omega$$

or in the multiplier notation

$$\mathbf{f} \bullet D\chi_\Omega + \chi_\Omega \bullet \operatorname{Div} \mathbf{f} = \mathbf{f} \chi_\Omega \bullet \mathcal{L}$$

where  $\mathcal{L}$  is the lebesgue measure regarded as distribution.

The most powerful versions of the Gauss-Green theorem are fairly complicated. We present here a simple corollary, in which  $\Omega$  need not be of finite perimeter..

Our aim is to prove that

$$\int \mathbf{f} d(D\chi_\Omega) + \int \chi_\Omega d(\operatorname{Div} \mathbf{f}) = \operatorname{Div} \int \mathbf{f} \chi_\Omega$$

or in the multiplier notation

$$\mathbf{f} \bullet D\chi_\Omega + \chi_\Omega \bullet \operatorname{Div} \mathbf{f} = \mathbf{f} \chi_\Omega \bullet \mathcal{L}$$

where  $\mathcal{L}$  is the lebesgue measure regarded as distribution.

The most powerful versions of the Gauss-Green theorem are fairly complicated. We present here a simple corollary, in which  $\Omega$  need not be of finite perimeter..

### Theorem (J.M.)

*Suppose that  $\Omega \subset \mathbb{R}^n$  is a bounded open set with a countably  $(n-1)$ -rectifiable boundary. Let  $\mathbf{f} \in C(\overline{\Omega}) \cap W^{1,1}(\Omega)$  be a vector field. Then*

$$\int_{\Omega} \operatorname{div} \mathbf{f}(x) dx = \int_{\partial\Omega} \mathbf{f} \cdot d\nu,$$

*where the integral on the right is understood as the packing integral of  $\mathbf{f}$  with respect to  $\nu = -D\chi_\Omega$ .*

Our aim is to prove that

$$\int \mathbf{f} d(D\chi_\Omega) + \int \chi_\Omega d(\operatorname{Div} \mathbf{f}) = \operatorname{Div} \int \mathbf{f} \chi_\Omega$$

or in the multiplier notation

$$\mathbf{f} \bullet D\chi_\Omega + \chi_\Omega \bullet \operatorname{Div} \mathbf{f} = \mathbf{f} \chi_\Omega \bullet \mathcal{L}$$

where  $\mathcal{L}$  is the lebesgue measure regarded as distribution.

The most powerful versions of the Gauss-Green theorem are fairly complicated. We present here a simple corollary, in which  $\Omega$  need not be of finite perimeter..

### Theorem (J.M.)

*Suppose that  $\Omega \subset \mathbb{R}^n$  is a bounded open set with a countably  $(n-1)$ -rectifiable boundary. Let  $\mathbf{f} \in C(\overline{\Omega}) \cap W^{1,1}(\Omega)$  be a vector field. Then*

$$\int_{\Omega} \operatorname{div} \mathbf{f}(x) dx = \int_{\partial\Omega} \mathbf{f} \cdot d\nu,$$

*where the integral on the right is understood as the packing integral of  $\mathbf{f}$  with respect to  $\nu = -D\chi_\Omega$ .*



Stokes theorem?

## Stokes theorem?

- in the euclidean setting, a notable version is not yet established.
- may build on recent developments in GMT of currents, chains, cochains, charges,.. J. Harrison; T. De Pauw, L. Moonens and W. Pfeffer 2009; T. De Pauw and R. Hardt 201x.

# Integration in metric spaces

The generalization to metric spaces is a joint work with Kristýna Kuncová. Instead of smooth test functions we use Lipschitz test functions and norms of order at most 1, The Lipschitz norm seems to be the most natural choice, so that we set

$$\mathbf{p}_{X,r}(\varphi) = \|\varphi\|_{\infty} + r\|\varphi\|_{\text{Lip}}.$$

(One can regard this as a model case and generalize to other norms. e.g. Sobolev type norms on metric spaces.)

# Integration in metric spaces

The generalization to metric spaces is a joint work with Kristýna Kuncová. Instead of smooth test functions we use Lipschitz test functions and norms of order at most 1, The Lipschitz norm seems to be the most natural choice, so that we set

$$\mathbf{p}_{X,r}(\varphi) = \|\varphi\|_{\infty} + r\|\varphi\|_{\text{Lip}}.$$

(One can regard this as a model case and generalize to other norms. e.g. Sobolev type norms on metric spaces.)

Dual objects to Lipschitz functions (weak\* continuous functionals on compactly supported Lipschitz functions) are called *metric distributions*. We integrate families of metric distributions and the indefinite integral is a metric distribution.

- If the space admits a doubling measure, then the packing integral is well defined.

- If the space admits a doubling measure, then the packing integral is well defined.
- The result on the measure control is also available.

- If the space admits a doubling measure, then the packing integral is well defined.
- The result on the measure control is also available.
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.

- If the space admits a doubling measure, then the packing integral is well defined.
- The result on the measure control is also available.
- The Lebesgue integral with respect to a Radon measure  $\mu$  is included.
- The packing integral allows for a bilipschitz change of variables.



We need the setting of currents on metric spaces: L. Ambrosio and B. Kirchheim 2000, related work T. De Pauw, R. Hardt,...

Roughly, a metric **1-current** is a bilinear weak\* continuous functional  $\mathcal{T}$  on “forms”  $\varphi d\psi$ , where  $(\varphi, \psi)$  is a pair of Lipschitz functions with compact spt  $\varphi\psi$ . The definition also requires: if  $\psi$  is constant on  $\{\varphi \neq 0\}$ , then  $\mathcal{T}(\varphi d\psi) = 0$ .

The **boundary** of a metric 1-current  $\mathcal{T}$  is the metric distribution

$$\partial\mathcal{T} : \varphi \mapsto \mathcal{T}(1 d\varphi).$$

We are interested in validity of the product rule

$$\partial(\mathbf{f} \bullet \mathcal{T}) = \mathbf{f} \bullet \partial(\mathbf{g} \bullet \mathcal{T}) + \mathbf{g} \bullet \partial(\mathbf{f} \bullet \mathcal{T}).$$

Here the currents can be vector valued. For  $\mathbf{g} = \chi_{\Omega}$  we obtain the Gauss-Green-Stokes formula. Indeed, let us observe the “translation table”, on the right we have the classical case of the divergence theorem.

A 1-current $\mathcal{T}$ is given	$\mathcal{T}(\varphi d\psi) = \int_{\mathbb{R}^n} \varphi \nabla \psi dx$
$\mathbf{f} \bullet \mathcal{T}(\varphi d\psi)$	$\int_{\mathbb{R}^n} f \varphi \nabla \psi dx$
$\partial(\mathbf{f} \bullet \mathcal{T})(\varphi)$	$\int_{\mathbb{R}^n} f \nabla \varphi = - \int_{\mathbb{R}^n} \varphi \operatorname{div} f dx$
$\chi_{\Omega} \bullet \partial(\mathbf{f} \bullet \mathcal{T})(\varphi)$	$- \int_{\Omega} \varphi \operatorname{div} f dx$
$\chi_{\Omega} \bullet \mathcal{T}(\varphi d\psi)$	$\int_{\Omega} \varphi \nabla \psi dx$
$\partial(\chi_{\Omega} \bullet \mathcal{T})(\varphi)$	$\int_{\Omega} \nabla \varphi dx = \int_{\partial\Omega} \varphi \cdot \nu d\mathcal{H}^{n-1}$
$\mathbf{f} \bullet \partial(\chi_{\Omega} \bullet \mathcal{T})(\varphi)$	$\int_{\partial\Omega} f \varphi \cdot \nu d\mathcal{H}^{n-1}$
$\partial(\mathbf{f} \chi_{\Omega} \bullet \mathcal{T})(\varphi)$	$- \int_{\Omega} f \cdot \nabla \varphi dx$

At the end, in the classical model the formula

$$\partial(\mathbf{f}\chi_{\Omega} \bullet \mathcal{T}) = \mathbf{f} \bullet \partial(\chi_{\Omega} \bullet \mathcal{T}) + \chi_{\Omega} \bullet \partial(\mathbf{f} \bullet \mathcal{T})$$

gives

$$-\int_{\Omega} \mathbf{f} \cdot \nabla \varphi \, dx = \int_{\partial\Omega} \varphi \mathbf{f} \cdot d\boldsymbol{\nu} - \int_{\Omega} \varphi \operatorname{div} \mathbf{f} \, dx.$$

If the test function equals 1 on  $\overline{\Omega}$ , we obtain

$$\int_{\partial\Omega} \mathbf{f} \cdot d\boldsymbol{\nu} = \int_{\Omega} \operatorname{div} \mathbf{f} \, dx.$$

We are able to prove the product rule

$$\partial(\mathbf{f}\mathbf{g} \bullet \mathcal{T}) = \mathbf{f} \bullet \partial(\mathbf{g} \bullet \mathcal{T}) + \mathbf{g} \bullet \partial(\mathbf{f} \bullet \mathcal{T})$$

under some complicated technical assumptions, which however are not as restrictive as they look like.